

## Overview

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- typing “`man function`” on the command line will bring up the “man-page” which describes the function
- many of the functions have corresponding UNIX command line programs: make sure you are looking at the man-page for the function
- almost all of the functions return a `-1` for failure and `0` for success
- if a function fails it sets the `errno` value with a number corresponding to the type of error – the numbers can be found in the `errno.h` include file



## fork()

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- fork() spawns an identical child process

```
#include <sys/types.h>
#include <unistd.h>
```

```
pid_t fork(void);
```

- example:

```
pid_t pid;
```

```
pid = fork();
if( pid == 0 ) {
    // only the child should get here
    while( 1 )
        printf( "I am the child\n" );
} // end if // only the parent should get here
```

## execl()

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- `execl()` replaces a process with an executable piece of code
- `arg0` is traditionally the name of executable
- list of arguments must end with a `NULL`

```
#include <unistd.h>
```

```
int execl(const char *path, const char *arg0, ...,
          const char *argn, char * /*NULL*/);
```

- example:

```
pid = fork();
if( pid == 0 )
    execl( "keyboard", "keyboard", 0 );
// run the keyboard executable
```

## getpid()

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- getpid() returns the current process' id

```
#include <sys/types.h>
```

```
#include <unistd.h>
```

```
pid_t getpid(void);
```

- example:

```
pid_t pid;
```

```
pid = getpid();
```

## kill()

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- kill() sends a signal to a process

```
#include <sys/types.h>
#include <signal.h>
```

```
int kill(pid_t pid, int sig);
```

- example:

```
pid = getpid();
kill( pid, SIGQUIT );
```

## usleep()

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- `usleep()` suspends the current process for “useconds” micro-seconds

```
#include <unistd.h>
```

```
int usleep(unsigned int useconds);
```

- example:

```
printf( "wake me up in a second\n" );  
usleep( 1000000 );  
printf( "I woke up!\n" );
```

## shmget()

- `shmget()` gets the identifier for a block of shared memory registered with value “key”
- “key” is decided by the programmer, “IPC\_PRIVATE” will return the next available key – this key can’t shared
- different values for “shmflag” change how the shared memory is retrieved
- “IPC\_CREAT” is specified to create new memory

```
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
```

```
int shmget(key_t key, int size, int shmflg);
```

- example:

```
int smem, smem2;
```

```
smem = shmget( IPC_PRIVATE, 100, 0 );
smem2 = shmget( 0x30, 100, IPC_CREAT );
```

## ftok()

- `ftok()` returns an identifier based on a file name
- allows easy exchange of keys for IPC functions

```
#include <sys/types.h>
#include <sys/ipc.h>
```

```
key_t ftok(const char *path, int id);
```

- example:

```
key_t iKey;
```

```
iKey = ftok( "/u4/ctrudeau/queues", 3 );
```



## shmctl()

- shmctl() controls a block of shared memory
  - “IPC\_STAT” get status info of block
  - “IPC\_SET” change permissions and ownership
  - “IPC\_RMID” remove a block

```
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
```

```
int shmctl(int shmid, int cmd, struct shmid_ds *buf);
```

- example:

```
int smem;

smem = shmget( IPC_PRIVATE, 100, 0 );
shmctl( smem, IPC_RMID, NULL );
// deletes sh mem block
```



## shmat()

- `shmat()` associates a local block of memory with a shared block of memory
- provides a memory mapped interface to shared memory

```
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
```

```
void *shmat(int shmid, void *shmaddr, int shmflg);
```

- example:

```
int smem;
void *my_mem;
```

```
smem = shmget( IPC_PRIVATE, 100, 0 );
my_mem = shmat( smem, 0, MSG_R | MSG_W );
```

## msgget()

- `msgget()` gets a pointer to a message queue
- “key” is the identifier for the queue – see “`ftok()`”
- “msgflg” sets permissions and creation flags
  - “`IPC_CREAT`” create the queue
  - “`IPC_EXCL`” disallow attaching to existing queue

```
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/msg.h>
```

```
int msgget(key_t key, int msgflg);
```

- example:

```
iPerm = MSG_R | MSG_W | MSG_R >> 3 | MSG_W >> 3;
iPerm |= IPC_CREAT | IPC_EXCL;
iMsgId = msgget( iKey, iPerm );
```

## msgctl()

- msgctl() controls a message queue
  - “IPC\_STAT” get queue status information
  - “IPC\_SET” set permissions and ownership
  - “IPC\_RMID” remove a queue

```
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/msg.h>
```

```
int msgctl(int msqid, int cmd, struct msqid_ds *buf );
```

- example:

```
iRet = msgctl( iMsgId, IPC_RMID, 0 );
```

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## msgsnd() & msgrcv()

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- msgsnd() & msgrcv() send and receive messages
  - “IPC\_NOWAIT” don't block for the message
- all message structures passed should begin with an integer which indicates the message type
- the message type field is not included in the size calculation

```
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/msg.h>
```

```
int msgsnd(int msqid, const void *msgp, size_t msgsz,
           int msgflg);
```

```
int msgrcv(int msqid, void *msgp, size_t msgsz,
           long msgtyp, int msgflg);
```

## Send & Receive Examples

```
typedef struct _m_init
{
    int iType;
    char cEXNum;
} m_init;
```

```
m_init pMsg;
```

```
:
```

```
iRet = msgsnd( iMsgId, pMsg, msgSize - sizeof( int ),
               0 );
```

```
iRet = msgsnd( iMsgId, pMsg, msgSize - sizeof( int ),
               IPC_NOWAIT );
```

```
iRet = msgrcv( iMsgId, pMsg, msgSize - sizeof( int ),
               msgType, 0 );
```